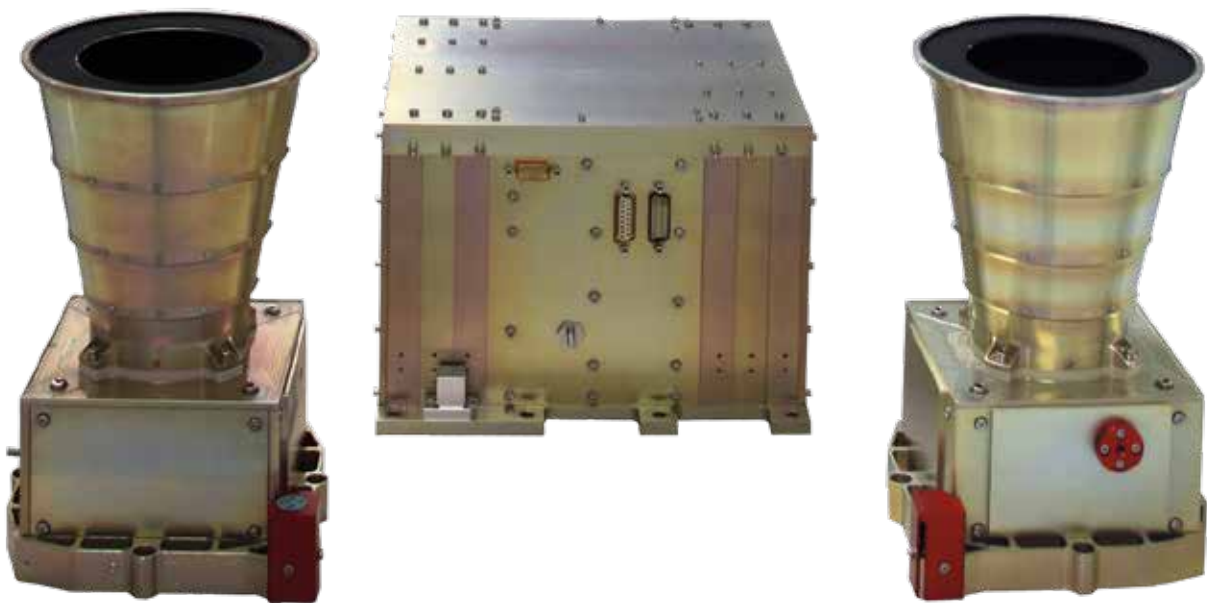


## ASTROgyro™

The Jena-Optronik **ASTROgyro** unfolds the synergies of star trackers and gyroscopes.



Unfolding the synergies of star trackers and gyroscopes, **ASTROgyro™** establishes a reliable and performant attitude determination system by combining Jena-Optronik's successful **ASTRO** star tracker series, as source of absolute and drift-free attitude information based on star pattern recognition, with the broad dynamic range and low noise rate spectrum of inertial sensing technology.

## ASTROgyro Performance

|   | ASTROgyro Star Sensor (AGS)<br>ASTRO APS  | ASTROgyro IRU (AGI)<br>Inertial Reference Unit   |
|---|---|--|
| <b>System Design &amp; Performance (typical)</b>                      |   |  |
| Technology  | APS CMOS detector chip, radiation hard  | Coriolis Vibratory Gyroscope (CVG)   |
| System Concept  |   | 2 x AGS<br>1 x AGI (2 x 3-Axis Gyro Units)<br>AGS and AGI cross-strapped   |
| Output  | Rate and attitude quaternions from merged AGS and AGI data (raw data available)                 |  |
| Random Attitude Error, typical  | ~ 1 arcsec (1 $\sigma$ ), all axes  |  |
| Random Rate Error, typical  | ~ 4 arcsec/sec (1 $\sigma$ ), all axes  |  |
| Gyro-Assisted Attitude Bridging (Star Tracker AGS denied, Earth Rate) | Typical 0.1 deg accuracy over a time period of 1000 sec   |  |
| <b>Interfaces &amp; Operations</b>                                    |   |  |
| Update Rate   | 30 Hz (drift-free IRU data aided by 10 Hz STR updates)  |  |
| Reliability   | ~ 0.981 (Probability of Success, 45°C, 15 years)  |  |
| Data Interfaces   | MIL-STD-1553B (other data interfaces on request)  |  |
| Power Interface   | 28V nominal (customized versions on request)  |  |
| Power Consumption   | < 6 W (Peltier Cooler OFF)<br>< 12 W (Peltier Cooler ON)  | < 15 W (cold-redundant)<br>< 30 W (hot-redundant)<br>< 21 W (nominal min., system 1 x AGS & 1 x AGI cold-redundant)<br>< 54 W (nominal max., system 2 x AGS & 1 x AGI hot-redundant) |
| <b>Size &amp; Mass</b>  |   |  |
| Dimensions  | 154 mm x 154 mm x 237 mm (single unit)  | ~ 230 mm x 230 mm x 170 mm   |
| Mass  | approx. 2 kg (single unit)  | approx. 7.8 kg   |
| <b>Temperature Range</b>  |   |  |
| Operational   | -30 °C ... +60 °C   | -30 °C ... +65 °C (full performance)   |
| Non-operational   | -40 °C ... +70 °C   | -55 °C ... +85 °C  |
| <b>Gyro Performance Characteristics (typical)</b>                     |   |  |
| Full Scale Range  | +/- 20 deg/sec (coarse), +/- 1 deg/sec (fine)   |  |
| Angle Random Walk   | < 0.005 deg/ $\sqrt{\text{hr}}$ , per axis  |  |
| Noise Equivalent Angle  | < 0.2 arcsec (1 $\sigma$ ), per axis  |  |
| Noise Equivalent Rate   | < 2 deg/hr r.m.s (0.1 Hz ... 15 Hz), per axis   |  |
| Bias Instability  | < 0.05 deg/hr (1 $\sigma$ ), per axis (Allan deviation)   |  |
| Scale Factor Error  | < 3500 ppm (1 $\sigma$ ), per axis  |  |
| <b>Star Sensor Performance Characteristics (typical)</b>              |   |  |
| Bias Error  | < 5 arcsecs (full temperature range)  |  |
| Noise Equivalent Angle  | < 1 arc-sec (1 $\sigma$ , xy-axis) , < 8 arc-sec (1 $\sigma$ , z-axis)                          |  |
| Acquisition Time  | < 10 sec (switch-on)<br>< 5 sec (re-acquisition, lost-in-space)                                 |  |
| Stray Light   | Sun: 26 deg Sun Exclusion Angle<br>Earth: 20 deg Earth Exclusion Angle<br>Moon: accepted in FoV |  |